## **Two-Axis Motion Simulator Model AC2237**



The Series AC2237 Two-Axis Test Tables are part of an economic series of rate tables. The model allows testing of several medium Inertial Measurement Units (IMU's) or Micro Electro Mechanical Systems (MEMS) sensors simultaneously.

The axes are driven by direct drive brushless motors. The brushless motors offer excellent torque and since they have no wear parts the reliability is excellent. AC drive amplifiers produce the required current to power the motors. The table features excellent instantaneous rate stability and precise, stable absolute positioning.

The elevation axis is equipped with a stow lock to facilitate the safe loading/unloading of the UUT.

Slipring capsules take the signals and or power from the table base to the device under test. ACUTRONIC offers three standard slipring packages for better economy.

The table is controlled by the ACUTROL®3000 digital controller. The controller has a touch sensitive display and a scalable analog input/output interface. Optionally, the standard digital interfaces of IEEE-488 and Ethernet (TCP/IP) can be supplemented with VMIC or SCRAMNet reflective memory interfaces. For more details, please refer to the ACUTROL®3000 datasheet.

# ACUTRONIC

Dimensions	Height, max	mm	1230
	Height of outer axis	mm	750
	Width across outer axis	mm	1335
	Base dimension	mm	1250x750 (LxW)
	Table top diameter	mm	300 (20xM6 helicoils)
	Table top offset	mm	87
	Table top flatness	mm	0.05
Unit Under Test (UUT)	Payload weight	kg	20 (nominal)
	Clearance envelope	mm	300 x 350 (ØxH)

Mech. specifications	Inner Axis	Outer Axis	
Orthogonality	+/-5"		
Wobble	<5"	<5''	
Static and dynamic			
performances			
Angular freedom	Continuous	Continuous	
Positioning accuracy	5 arcsec RSS	5 arcsec RSS	
Rate range	+/-1'500°/s	+/-600°/s	
Acceleration, no load	1'500°/s <sup>2</sup>	400°/s <sup>2</sup>	
with load	Inertia load dependent	Inertia load dependent	

Slipring Configuration according to standard wiring schematics			
	Ways	Connectors	
Wiring Typ 1A	70 lines rated 2A, 150VDC	2x 37pin D-Sub	
Wiring Typ 2A	45 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+10 lines rated 5A, 150VAC	1x 15pin D-Sub	
Wiring Typ 3A	45 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+4 lines rated 20A, 400VDC	1x 5pin D-Sub (5W5)	

#### Options

- Standard (450mm) or customized (up to max. 450mm) table top (dynamic specification subject to change)
- RF (up to 18GHz) rotary joints for GPS signals
- Base template
- North alignement kit (requires base template option)

#### Installation requirements

• 3 x400VAC +/-8% with ground (PE; no neutral required), 50/60Hz, 16Amps fused.

#### Packing details (approximate)

- Box 1 (simulator): 220x105x140cm (WxDxH), Grossweight: 670kg, Netweight: 435kg
- Box 2 (console): 85x100x235cm (WxDxH), Grossweight: 440kg, Netweight: 285kg

#### **Delivery time**

• 6 months average

Internet: www.acutronic.com

## **Two-Axis Motion Simulator Model AC2237-TC**



The Series AC2237-TC Two-Axis Test Tables are part of an economic series of rate tables.

The model allows testing of several medium Inertial Measurement Units (IMU's) or Micro Electro Mechanical Systems (MEMS) sensors simultaneously.

The axes are driven by direct drive brushless motors. The brushless motors offer excellent torque and since they have no wear parts the reliability is excellent. AC drive amplifiers produce the required current to power the motors. The table features excellent instantaneous rate stability and precise, stable absolute positioning.

The elevation axis is equipped with a stow lock to facilitate the safe loading/unloading of the UUT within the temperature chamber. There are two cooling systems offered: cooling by the expansion of either Liquid Nitrogen  $LN_2$  (-TCN) or Carbon Dioxide  $CO_2$  gas (-TCC).

Slipring capsules take the signals and or power from the table base to the device under test. ACUTRONIC offers three standard slipring packages for better economy.

The table is controlled by the ACUTROL®3000 digital controller. For more details, please refer to the ACUTROL®3000 datasheet.

Dimensions	Height, max	mm	1230
	Height of outer axis	mm	750
	Width across outer axis	mm	1335
	Base dimension	mm	1250x750 (LxW)
	Table top diameter	mm	300 (20xM6 helicoils)
	Table top offset	mm	25
	Table top flatness	mm	0.05
Unit Under Test (UUT)	Payload weight Clearance envelope	kg mm	20 (nominal) 300 x 240 (ØxH) inside chamber
Thermal Chamber	Temperature Range Cooling gradient Heating gradient Stability	degC degC/min degC/min degC	-55 / +100 -4 +4 +/-1.5

Mech. specifications	Inner Axis	Outer Axis	
Orthogonality	+/-5 arcsec		
Wobble	<5 arcsec	<5 arcsec	
Static and dynamic			
performances			
Angular freedom	Continuous	Continuous	
Positioning accuracy	5 arcsec RSS	5 arcsec RSS	
Rate range	+/-1'500°/s	+/-200°/s	
Acceleration, no load	1'500°/s <sup>2</sup>	200°/s <sup>2</sup>	
with load	Inertia load dependent	Inertia load dependent	

Slipring Configuration according to standard wiring schematics			
	Ways	Connectors	
Wiring Typ 1B	52 lines rated 2A, 150VDC	2x 37pin D-Sub	
Wiring Typ 2B	28 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+10 lines rated 5A, 150VAC	1x 15pin D-Sub	
Wiring Typ 3B	28 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+4 lines rated 20A, 400VDC	1x 5pin D-Sub (5W5)	

### Options

- Customized (up to max. 300mm) table top (dynamic specification subject to change)
- RF (up to 18GHz) rotary joints for GPS signals
- Base template
- North alignement kit (requires base template option)

#### Installation requirements

- 3 x400VAC +/-8% with ground (PE; no neutral required), 50/60Hz, 25Amps fused.
- CO<sub>2</sub> or LN<sub>2</sub> supply

### Packing details (approximate)

- Box 1 (simulator): 220x105x140cm (WxDxH), Grossweight: 690kg, Netweight: 455kg
- Box 2 (console): 85x100x235cm (WxDxH), Grossweight: 460kg, Netweight: 305kg