

Missile Motion Simulator for Infra Red (IR) seeker test

# **Three Axis Motion Simulator Model AC3355**

## **Modes of Operation**

- Absolute Positioning:
   0.00001 deg. resolution
- Rate absolute and relative, excellent instantaneous rate stability
- Track Mode for real time simulation of complex motion profiles
- Synthesis Mode Sinusoidal motion, command amplitude, frequency and phase.
- Local or remote control via touch sensitive operator panel or digital interface
- Analog readout and command with 16 bit resolution



#### **Feature**

High torque, direct drive, brushless motors produce high acceleration in all axes. The rigid structural design caters for high bandwidth applications and high fidelity real time motion simulation.

#### **Description**

The model AC3355 has been designed to test missiles and missile seekers that operate in the Infra-Red (IR) spectrum. A high speed Roll Barrel supports the missile with the seeker gimbal coincident with the simulator's axis intersection. The Roll Barrel can be moved in azimuth with high acceleration and rate. Electrical and gas sliprings at the rear of the Roll Barrel provide access for the necessary facilities of the missile seeker.

The surface plate or Look Angle Fixture (LAF) supports the target which, for simulation purposes, is typically point source IR and associated collimator. The collimated beam is directed onto the missile seeker. The LAF can be moved in front of the missile in azimuth to simulate motion of the target and off bore-sight testing.



Saddle mounting surfaces on the side of the missile azimuth axis support the customer electronics for the IR source and missile control.

A gantry assembly above the axis intersection supports the customer droop cables and gas lines.

The ACUTROL® Model ACT3000 controls the table. The digital controller has a touch sensitive operator interface and scalable analog input/output interface. Programmable Event Pulses can be used for calibration and synchronization with external computers or test equipment. Optionally, the standard digital interfaces, Ethernet (TCP/IP) and IEEE-488 can be supplemented with real time reflective memory interfaces SCRAMNet or VMIC.

### **Dimensions**

	Height, max Length Turn radius of Look Angle Fixture Look Angle Fixture Hole pattern	1525 mm 2200 mm 2200 mm M6 x 50mm grid	
	Base, diameter	800 mm	
Unit under Test (UUT)	Payload, nominal LAF Payload, peak Roll Barrel Gas line through slipring Slipring lines through Roll Barrel (standard, options available)	30 Kg 13 Kg One :	2 x 10A 5 x 5A 65 x 2A

_	Miss	Target	
	Roll	Azimuth	Look Angle Fixture, <b>Azimuth</b>
Orthogonality	15 arcsec +/- 5		arcsec
Wobble	2 arcsec	5 arcsec	2 arcsec
<b>Dynamic Parameters</b>			
Angular freedom	continuous	continuous	+/-95 degs
Positioning accuracy	3,6 arcsec RSS	3,6 arcsec RSS	3,6 arcsec RSS
Position resolution	0.00001 deg	0.00001 deg	0.00001 deg
Rate range	+/-300 deg/s	+/-300 deg/s	+/-300 deg/s
Rate resolution	0.0001 deg/s	0.0001 deg/s	0.0001 deg/s
Rate accuracy	0.005%	0.005%	0.005%
Installed torque	40 Nm	1000 Nm	300 Nm
Inertia no load	0.25 kgm <sup>2</sup>	25 kgm²	14 kgm²
Acceleration, no load	4'800 deg/s <sup>2</sup>	1'100 deg/s2	1100 deg/s <sup>2</sup>
Bandwidth (-3dB)	60 Hz	25 Hz	Not applicable

## **Options**

- Digital interface in addition to the std. IEEE-488 and Ethernet (TCP/IP) optional available are: SCRAMNet, or VMIC
- Roll barrel may be deleted
- Larger torque motors for increased acceleration

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